

On constrained distribution-free p-boxes and their propagation

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Outline

Limitations of distribution-free p-boxes

Introducing constrained distribution-free p-boxes

Basics of distribution free p-boxes

Definitions

- X : real-valued random variable
- F_X : cumulative distribution function (CDF)

$$F_X : \mathbb{R} \rightarrow [0, 1], x \mapsto F_X(x) = P(X \leq x) \quad (1)$$

non-decreasing, right-continuous, and converges to 0 for $x \rightarrow -\infty$ and to 1 for $x \rightarrow \infty$

- $\mathcal{F}$: set of all CDFs on $\mathbb{R}$

Distribution free p-box

A set of possible CDFs for X is provided by a pair of an upper CDF $\overline{F}_X$ and a lower CDF $\underline{F}_X$:

$$[\overline{F}_X, \underline{F}_X] = \{F_X \in \mathcal{F} \mid \underline{F}_X(x) \leq F_X(x) \leq \overline{F}_X(x), x \in \mathbb{R}\} \quad (2)$$

Example: Feasible CDFs of a distribution-free p-boxes

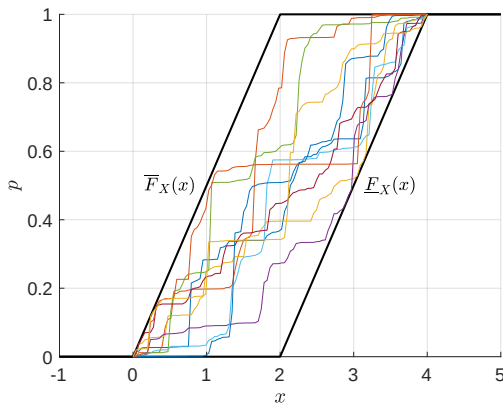


Figure: P-box bounds of a distribution free p-box $[\overline{F}_X, \underline{F}_X]$ with examples of feasible CDFs

Propagation of distribution free p-boxes considering the 2D Rosenbrock function

Input X_1 and X_2 with feasible CDFs within the envelope of normal distributions with $\mu \in [-0.5, 0.5]$ and $\sigma \in [0.7, 1]$:

$$\overline{F}_{X_i}(x_i) = \max_{\mu \in [-0.5, 0.5], \sigma \in [0.7, 1]} F_{\mathcal{N}}(x_i, \mu, \sigma) \quad (3)$$

$$\underline{F}_{X_i}(x_i) = \min_{\mu \in [-0.5, 0.5], \sigma \in [0.7, 1]} F_{\mathcal{N}}(x_i, \mu, \sigma) \quad (4)$$

Computational model 2D Rosenbrock function

$$\mathcal{M}(x) = 100(x_2 - x_1^2)^2 + (1 - x_1)^2 \quad (5)$$

Output Y with $F_Y \in [\overline{F}_Y, \underline{F}_Y]$

Example: what are the input CDFs responsible for $\overline{F}_Y(80)$ and $\underline{F}_Y(80)$?

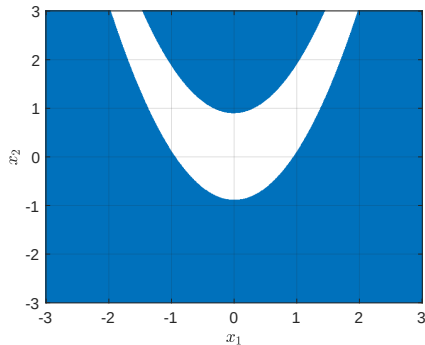
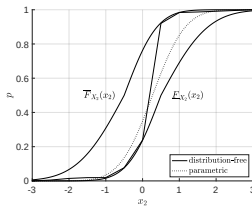
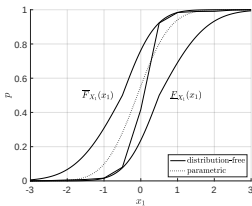


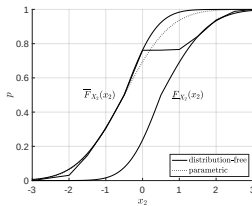
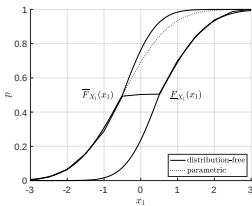
Figure: Set of x with $\mathcal{M}(x) \leq 80$ (white region) and $\mathcal{M}(x) > 80$ (blue region)

$\overline{F}_Y$ and $\underline{F}_Y$ can be a result of input CDFs $F_X \in [\overline{F}_X, \underline{F}_X]$ that could be considered unlikely for specific engineering applications

$$\overline{F}_Y(80) = 0.90$$



$$\underline{F}_Y(80) = 0.16$$



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Limitations of distribution-free p-boxes

Introducing constrained distribution-free p-boxes

Basics of constrained distribution free p-boxes

Idea

- Constrain the feasible CDFs of a distribution-free p-box in a non-parametric way
- For example, by upper and lower bounds for the moments of X , the PDF f_X , or further derivatives
- For example, by constraints on the distributional shape, e.g., for symmetry or unimodality

Constrained distribution free p-box

The distribution free p-box is intersected with a set of feasible CDF $\mathcal{F}' \subseteq \mathcal{F}$ that only comprises CDFs fulfilling additional constraints:

$$[\overline{F}_X, \underline{F}_X]' = [\overline{F}_X, \underline{F}_X] \cap \mathcal{F}'. \quad (6)$$

Note: There are some approaches in literature that could be considered as constrained distribution free p-boxes. However, appropriate techniques on how to handle additional p-box constraints computationally are lacking.

Distribution free p-boxes vs. constrained distribution free p-boxes

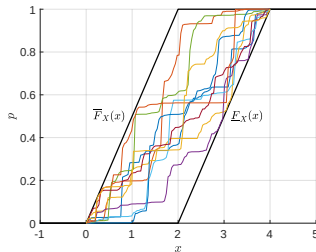


Figure: P-box bounds of a distribution free p-box $[\overline{F}_X, \underline{F}_X]$ with examples of feasible CDFs

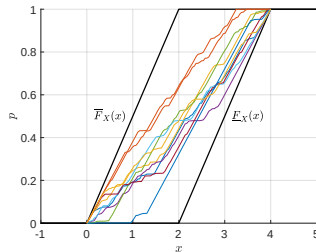


Figure: P-box bounds of a constrained distribution free p-box $[\overline{F}_X, \underline{F}_X]'$ (upper bound on the PDF) with examples of feasible CDFs

Numerics with constrained distribution-free p-boxes

Idea

- An (equidistant) grid on the interval $[\underline{x}, \bar{x}]$ with N inner grid points x_h^j is considered
- $F_{X,h}^j$ denote the values of F_X at the grid points (assume $F_{X,h}^0 = 0$ and $F_{X,h}^{N+1} = 1$)
- To guarantee that F_X is a proper CDF which is an element of the p-box $[\overline{F}_X, \underline{F}_X]$, $F_{X,h}^j$ must fulfill

$$F_{X,h}^j \leq F_{X,h}^{j+1}, \quad (7)$$

$$F_{X,h}^j \leq \overline{F}_X(x_h^j), \quad (8)$$

$$F_{X,h}^j \geq \underline{F}_X(x_h^j), \quad (9)$$

- As a simple approach, linear interpolation is used for the values of F_X at non-grid points
- Additional constraints, like a lower bound $\underline{f} \in \mathbb{R}$ and an upper bound $\overline{f} \in \mathbb{R}$ on the PDF can be introduced as an additional inequality

$$\underline{f} \leq \frac{F_{X,h}^{j+1} - F_{X,h}^j}{h} \leq \overline{f} \quad (10)$$

Propagating constrained distribution-free p-boxes

Approach

- Multiple random variables X_i are considered (assuming statistical independence)
- When propagating X_i through a computational model $\mathcal{M}$, F_Y is determined by the function values of the marginal CDFs F_{X_i} at the grid points and hence:

$$\overline{F}_Y(y) = \max_{\mathbf{F}_{\mathbf{X},h} \in \mathcal{S}'_{\mathbf{F}_{\mathbf{X},h}}} F_Y(y, \mathbf{F}_{\mathbf{X},h}), \quad (11)$$

$$\underline{F}_Y(y) = \min_{\mathbf{F}_{\mathbf{X},h} \in \mathcal{S}'_{\mathbf{F}_{\mathbf{X},h}}} F_Y(y, \mathbf{F}_{\mathbf{X},h}), \quad (12)$$

where $\mathcal{S}'_{\mathbf{F}_{\mathbf{X},h}}$ is the set of $F_{X,h}^j$ fulfilling inequalities (7)-(10)

- Monte Carlo simulation (MCS) with an inverse transform sampling is used for propagation (*for more advanced methods see: MGR Faes et al., Engineering analysis with probability boxes: a review on computational methods*)
- The resulting optimization problems are solved by a genetic algorithm

Back to the 2D Rosenbrock problem with constrained distribution-free p-boxes

Additional constraints for both F_{X_1} and F_{X_2} are introduced:

1. *No additional constraints*: This case corresponds to the case of distribution-free p-box (and was considered before).
2. *Bounds on the PDF*: An upper bound on the PDF is considered with

$$\bar{f} = \max_{x \in \mathbb{R}, \mu \in [-0.5, 0.5], \sigma \in [0.7, 1]} f_{\mathcal{N}}(x, \mu, \sigma) \approx 0.57,$$

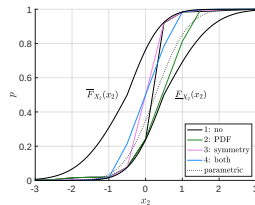
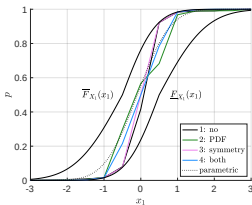
Here, $f_{\mathcal{N}}(\cdot, \mu, \sigma)$ is the PDF of a normal distribution with mean μ and standard deviation σ .

3. *Symmetry around 0*: A symmetry constraint around $x_1 = x_2 = 0$ is considered.
4. *Both bounds on the PDF and symmetry around 0*: The bounds on the PDF and the symmetry constraint around $x_1 = x_2 = 0$, as defined above, are considered.

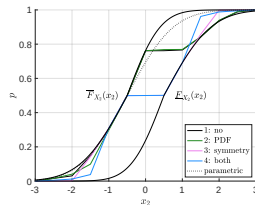
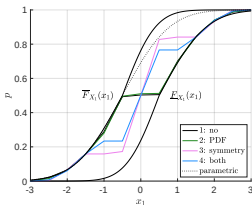
Input CDFs responsible for $\overline{F}_Y(80)$ and $\underline{F}_Y(80)$ (cases 1-4)

 $\overline{F}_Y(80)$

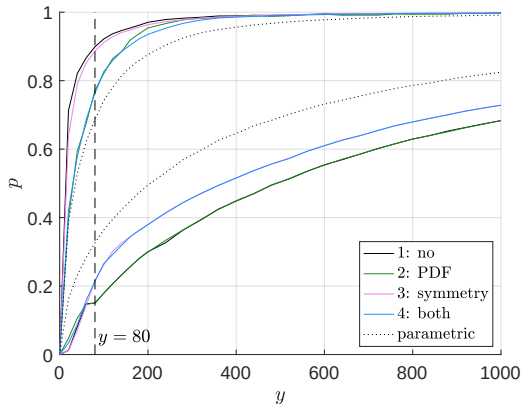
1 (no)	2 (PDF)	3 (sym)	4 (both)
0.90	0.76	0.88	0.76


 $\underline{F}_Y(80)$

1 (no)	2 (PDF)	3 (sym)	4 (both)
0.16	0.16	0.21	0.22



Graph of $\overline{F}_Y$ and $\underline{F}_Y$ of the constrained distribution-free p-boxes (cases 1-4)



Conclusion

Recap:

- A new p-box type, the constrained distribution-free p-box, which is based on distribution-free p-boxes plus a narrowing of the feasible CDFs, was proposed
- An approach, which is based on a discretization of the input space and on linear interpolation, was presented to treat them numerically
- The discretized p-boxes were propagated to p-boxes in the output space using Monte Carlo simulation and optimization

Key takeaways:

- Constraint distribution-free p-boxes lead to bounds of the p-box in the output space that might be tighter than the ones from distribution-free p-boxes but also wider than the ones from parametric p-boxes
- Constrained distribution-free p-boxes can enhance uncertainty quantification for practical applications whenever more information than the information of bounds on the CDFs is available, but a limitation to a specific distribution is too restrictive

Thank you for your attention!